PT8CN CANbus • SAE J1939 Output Signal

Industrial Grade String Pot Absolute Linear Position to 60 inches (1524 mm) Aluminum or Stainless Steel Enclosure Options NEMA 6 / IP67

GENERAL

Full Stroke Ranges		0-2 to 0-60 inches
Electrical Interface		CANbus SAE J1939
Protocol		Proprietary B
Accuracy		see ordering information
Repeatability		\pm 0.02% full stroke
Resolution		± 0.003% full stroke
Measuring Cable Options	stain	less steel or thermoplastic
Enclosure Material	powder-painted a	lluminum or stainless steel
Sensor	plastic-hybri	d precision potentiometer
Potentiometer Cycle Life		see ordering information
Maximum Retraction Acceleration		see ordering information
Weight, Aluminum (Stainless Steel) Enclosure		3 lbs. (6 lbs.), max.

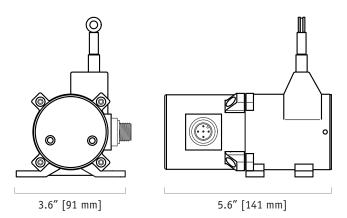
ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Baud Rate	125K, 250K, or 500K via DIP switches
Update Rate	10 ms. (20 ms. available, contact factory)

ENVIRONMENTAL

Environmental Suitability	NEMA 4X/6, IP 67
Operating Temperature	-40° to 185°F (-40° to 85°C)
Vibration	up to 10 g to 2000 Hz maximum





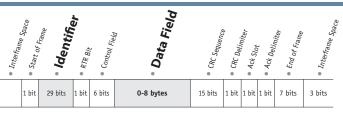
The PT8CN, using a high cycle plastic-hybrid potentiometer, communicates to your PLC via the CANbus SAE J1939 interface. Suitable for factory and harsh environment applications requiring linear position feedback in ranges up to 60".

As a member of our innovative family of NEMA 4 rated cable actuated sensors, the PT8CN installs in minutes by simply mounting it's body to a fixed surface and attaching it's cable to the movable object. Perfect parallel alignment not required.



Output Signal:

I/O Format and Settings



repetition = 8 msec.

Current % of

Measurement

Range

B₁

B₀

Identifier J1939 Reference Future Message Priority Data Field Type* Not Used Node ID** Proprietary B Example 1 0 0 0 0 1 1 1 1 1 1 1 1 0 1 0 1 0 0 1 1 0 0 1 1 1 1 1 1 Identifier Bit No. -28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 Hex Value -0 F F 5 3 3 F **Customer defined, set via Dips 1-6. Bit values shown for example only, see Address Setting below. *Sensor field data can be factory set to customer specific value.

Data Field

 B_0 = LSB current % of measurement range byte B_1 = MSB current % of measurement range byte

 B_2 = LSB current measurement count byte B_3 = MSB current measurement count byte

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable. The CMC is a 16-bit value that occupies bytes B_2 and B_3 of the data field. B_2 is the LSB (least significant byte) and B_3 is the MSB (most significant byte).

The **CMC** starts at **0x0000** with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **0xFFFF**. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 65,535 (total counts over the range) and then multiply that value by the full stroke range:

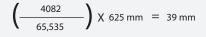


Sample Conversion:

If the full stroke range is **30 inches** and the current position is **0x0FF2** (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 30.00 inches = 1.87 inches

If the full stroke range is **625 mm** and the current position is **0x0FF2** (4082 Decimal) then,



formally Celesco Transducer Products, Inc celesco.com • info@celesco.com B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Current % of Measurement Range

The Current % of Measurement Range is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is **.1** % of the full stroke measurement range.

This value starts at 0x0000 at the beginning of the stroke and ends at 0x03E8.

Example:

B₄ = error flag **B**₅ = error flag

B6 = LSB velocity data byte

B7 = MSB velocity data byte

Hex	Decimal	Percent
0000	0000	0.0%
0001	0001	0.1%
0002	0002	0.2%
•••	•••	•••
03E8	1000	100.0%

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Error Flags

0x55 (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

0xAA (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Current

Measurement

Count

B₂

 B_3

Velocity

Error Flags

 B_4

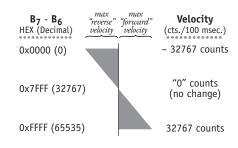
 B_5

Velocity Data

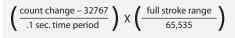
B₆

B₇

Data in bytes $B_7 - B_6$ is the change in the CMC (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.



Velocity Calculation



Sample Calculations

Cable Extension (positive direction):

B7-B6 = 0x89C6 (43462 Dec), full stroke = 60 in.

$$\left(\frac{35270-32767}{.1 \text{ sec}}\right) \times \left(\frac{60 \text{ in.}}{65,535}\right) = 22.92 \text{ in. / sec}$$

Cable Retraction (negative direction):

B₇-B₆ = 0x61A8 (25000 Dec), full stroke = 60 in.

$$\left(\frac{25000-32767}{.1 \text{ sec}}\right) X \left(\frac{60 \text{ in.}}{65,535}\right) = -71.11 \text{ in. / sec.}$$

Setting the Address (Node ID) and Baud Rate

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number 1 (= 2^0) and ending with switch number 6 (= 2^5).

DIP-1 (2 ⁰)	DIP-2 (2 ¹)	DIP-3 (2 ²)	DIP-4 (2 ³)	DIP-5 (2 ⁴)	DIP-6 (2 ⁵)	<i>address</i> (decimal)
0	0	0	0	0	0	0
1	0	0	0	0	0	1
0	1	0	0	0	0	2
•••		•••				
1	1	1	1	1	1	63

Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

DIP-8

0

0

1

1

baud rate

125k

250k

500k

125k

4

DIP-7

0

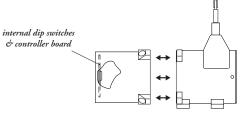
1

0

1

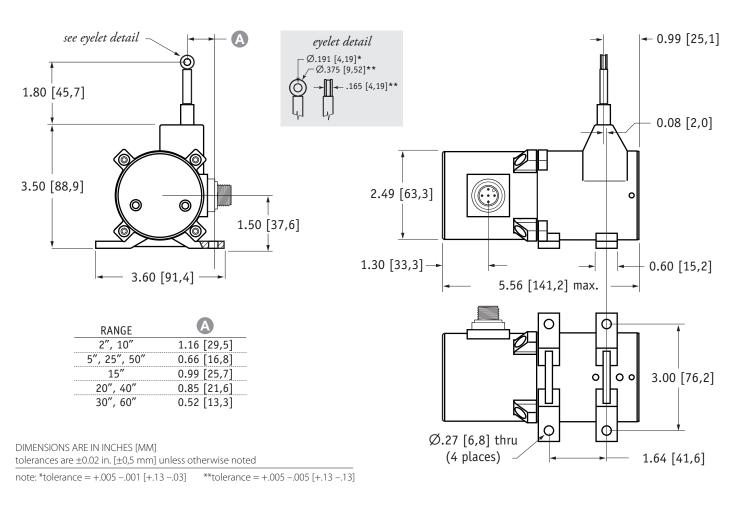
CANBus Controller Board





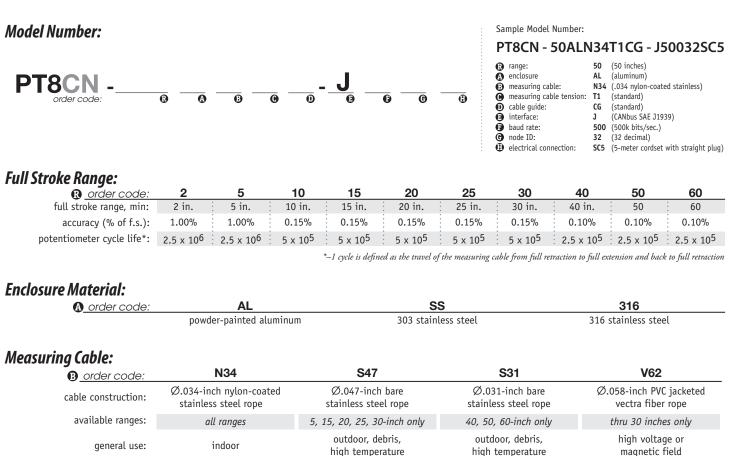
to gain access to the controller board, remove four Allen-Head Screws and remove rear cover.

Outline Drawing:



tel: 800.423.5483 • +1.818.701.2750 • fax: +1.818.701.2799 meas-spec.com formally Celesco Transducer Products, Inc. celesco.com • info@celesco.com

Ordering Information:



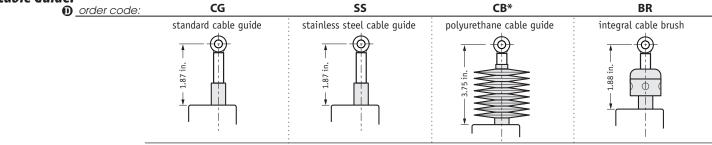
Measuring Cable Tension:

	© order code:	T1	T2	Т3
		standard tension	medium tension	high tension
full stroke range cable tension specifications	2, 10-inch:	39 oz.	65 oz.	116 oz.
	2 15-inch:	26 oz.	43 oz.	77 oz.
	.,	20 oz.	33 oz.	60 oz.
	5, 25, 50-inch:	16 oz.	26 oz.	47 oz.
	30, 60-inch:	13 oz.	22 oz.	40 oz.
				tension tolerance: ± 50%
		maximum acceleration	maximum acceleration	maximum acceleration
	aluminum enclosure:	15 g	25 g	40 g
stai	inless steel enclosure:	6 g	12 g	18 g

high temperature

high temperature

Cable Guide:



*note: all ranges up to 25 inches only

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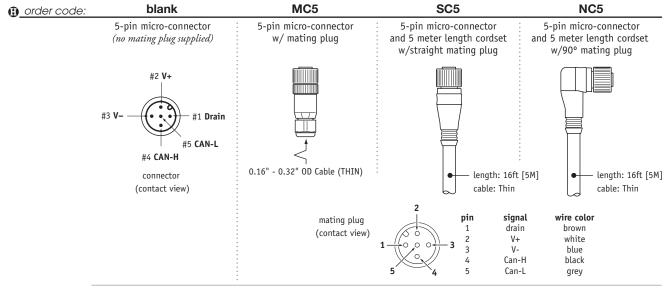
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Ordering Information (cont.):

Baud Rate:



Electrical Connection:





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