PT9CN

(Extended Range

Heavy Industrial • J1939 CANBus

Linear Position/Velocity to 1700 inches (4300 cm) Stroke Range Options: 0-600 to 0-1700 inches **VLS Option To Prevent Free-Release Damage IP68 • NEMA 6 Protection**

GENERAL

Full Stroke Range Options (on this	datasheet) 0-600 to 0-1700 inches
Electrical Signal Interface	CANbus SAE J1939
Protocol	Proprietary B
Accuracy	$\pm0.10\%$ full stroke
Repeatability	$\pm0.02\%$ full stroke
Resolution	$\pm0.003\%$ full stroke
Measuring Cable Options	nylon-coated stainless stee
Enclosure Material powd	er-painted aluminum or stainless steel
Sensor	plastic-hybrid precision potentiometer
Potentiometer Cycle Life	≥ 250,000 cycles
Maximum Retraction Acceleration	see ordering information
Maximum Velocity	see ordering information
Weight, Aluminum (Stainless Steel)	Enclosure 14 lbs. (28 lbs.), max.

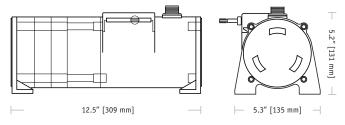
ELECTRICAL

Input Voltage	7 - 18 VDC
Input Current	60 mA max.
Address Setting/Node ID	063 set via DIP switches
Baud Rate	125K, 250K or 500K set via DIP switches
Update Rate	10 ms. (20 ms. available, contact factory)

ENVIRONMENTAL

Enclosure	NEMA 4/4X/6, IP 67
Operating Temperature	-40° to 200°F (-40° to 90°C)
Vibration	up to 10 g to 2000 Hz maximum

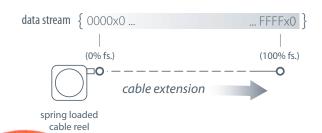




The PT9CN communicates linear position feedback via the CANbus SAE J1939 interface. The PT9CN has been designed for factory and harsh environment applications requiring full stroke ranges up to 1700".

As a member of our innovative family of NEMA 4 rated cable-extension transducers, the PT9CN installs in minutes by simply mounting it's body to a fixed surface and attaching it's cable to the movable object. Perfect parallel alignment not required.

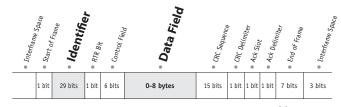
Output Signal:







I/O Format and Settings



repetition = 8 msec.

Current % of

Identifier

ier –	Mess	age Pr	iority	Fut U:	ure se				939 R Propri							Da	ta Fi	eld Ty	pe*			Not	Used		N	lode 1	D**		
Example –	1	0	0	0	0	1	1	1	1	1	1	1	1	0	1	0	1	0	0	1	1	0	0	1	1	1	1	1	1
Identifier Bit No. –	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Hex Value –			()			ı	F			ı	=				5			3	3			3	3			ı	=	

**Customer defined, set via Dips 1-6. Bit values shown for example only, see Address Setting below. *Sensor field data can be factory set to customer specific value.

Data Field

 $\mathbf{B_0}$ = LSB current % of measurement range byte **B**₁ = MSB current % of measurement range byte

 $\mathbf{B_2}$ = LSB current measurement count byte

B₃ = MSB current measurement count byte

B₄ = error flag	Veloci	ty Data	Error	Flags		rement unt	Measu Rai		
B ₅ = error flag		_							
B ₆ = LSB velocity data byte	B ₇	В ₆	B ₅	B ₄	B ₃	B ₂	B ₁	B ₀	



Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable. The CMC is a 16-bit value that occupies bytes B2 and B3 of the data field. B2 is the LSB (least significant byte) and B_3 is the MSB(most significant byte).

The CMC starts at 0x0000 with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at OxFFFF. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 65,535 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\frac{\frac{\text{current measurement}}{\text{count}}}{65,535}\right) \times \frac{\text{full stroke}}{\text{range}}$$

Sample Conversion:

If the full stroke range is 30 inches and the current position is OxOFF2 (4082 Decimal) then,

$$\left(\frac{4082}{65.535}\right)$$
 X 30.00 inches = 1.87 inches

If the full stroke range is 625 mm and the current position is OxOFF2 (4082 Decimal) then,

$$\left(\frac{4082}{65,535}\right)$$
 X 625 mm = 39 mm

B₇ B₆ B₅ B₄ B₃ B₂ B₁

Current % of Measurement Range

The Current % of Measurement Range is a 2-byte value that expresses the current linear position as a percentage of the entire full stroke range. Resolution is .1 % of the full stroke measurement range.

This value starts at 0x0000 at the beginning of the stroke and ends at 0x03E8.

Example:

Hex	Decimal	Percent
0000	0000	0.0%
0001	0001	0.1%
0002	0002	0.2%
	•••	
03E8	1000	100.0%

B ₇	В6	B ₅	B ₄	В3	B ₂	B ₁	B ₀	

Error Flags

0x55 (yellow LED on controller board) indicates that the sensor has begun to travel beyond the calibrated range of the internal position potentiometer.

OxAA (red LED on controller board) indicates that the sensor has moved well beyond the calibrated range of the internal position potentiometer.

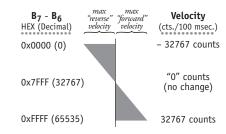
If either error flag occurs within the full stroke range of the sensor, the unit should be returned to the factory for repair and recalibration.

B₇ B₆ B₅ B₄ B₃ B₂ B₁ B₀

Current

Velocity

Data in bytes B7 - B6 is the change in the CMC (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.





Sample Calculations

Cable Extension (positive direction):

 $B_7 - B_6 = 0x80C6$ (32966 Dec), full stroke = 200 in.

$$\left(\frac{32966 - 32767}{.1 \text{ sec}}\right) X \left(\frac{200 \text{ in.}}{65,535}\right) = 6.07 \text{ in.} / \text{sec.}$$

Cable Retraction (negative direction):

 $B_7 - B_6 = 0x7F1A$ (32538 Dec), full stroke = 200 in.

$$\left(\frac{32538 - 32767}{.1 \text{ sec}}\right) \chi \left(\frac{200 \text{ in.}}{65,535}\right) = -6.99 \text{ in. / sec}$$

Setting the Address (Node ID) and Baud Rate

Address Setting (Node ID)

The Address Setting (Node ID) is set via 6 switches located on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

The DIP switch settings are binary starting with switch number 1 (= 20) and ending with switch number $6 (= 2^5)$.

DIP-3

 (2^2)

0

0

0

DIP-4

 (2^3)

0

0

0

DIP-5

 (2^4)

0

0

0

DIP-6

 (2^5)

0

0

0

address

0

2

63

Baud Rate

The transmission baud rate may be either factory preset at the time of order or set manually at the time of installation.

The baud rate can be set using switches 7 & 8 on the 8-pole DIP switch found on the DeviceNET controller board located inside the transducer.

DIP-8

0

1

DIP-7

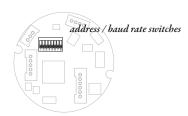
0

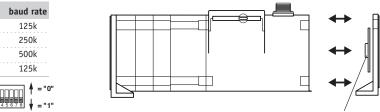
1

0

1

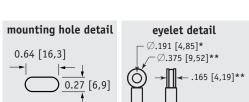
CANBus Controller Board

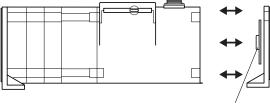




internal dip switches & controller board

to gain access to the controller board, remove four Allen-Head Screws and remove end cover bracket.





Outline Drawing

DTP-1

0

0

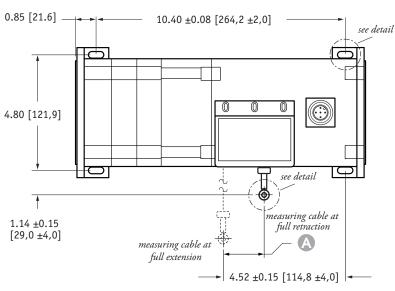
DIP-2

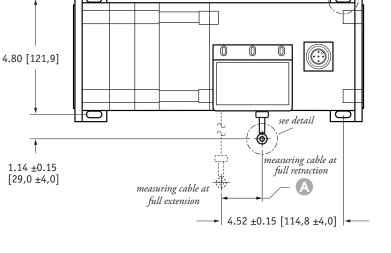
 (2^1)

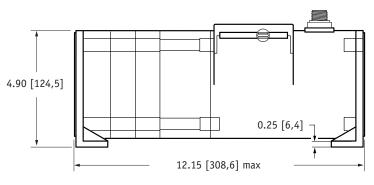
0

0

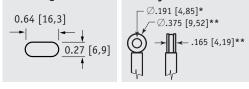
1





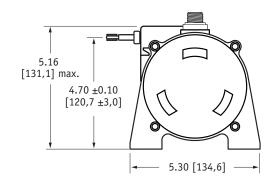


DIMENSIONS ARE IN INCHES [MM] tolerances are 0.03 IN. [0.5 MM] unless otherwise noted.



DIMENSION

RANGE	inches [mm]
600	1.76 [44,7]
800	1.58 [40,1]
1000	1.98 [50,2]
1200	1.98 [50,2]
1500	1.86 [47,2]
1700	2.11 [53,6]



- * tolerance = +.005 -.001 [+.13 -.03]
- ** tolerance = +.005 -.005 [+.13 -.13]

Ordering Information:

Model Number:

Sample Model Number:

PT9CN - 1200ALFR - J50032SC5

1200 (1200 inches) range: A enclosure (aluminum) ŏ cable exit: FR (front) interface: (CANbus SAE J1939) Ō baud rate: 500 (500k bits/sec.)

61

62

63

node ID: 32 (32 decimal) electrical connection: SC5 (5-meter cordset with straight plug)

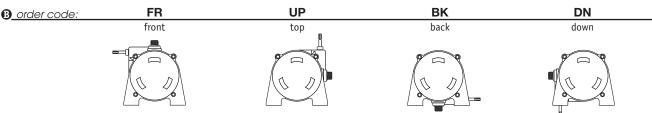
Full Stroke Ranae:

® <u>order code:</u>	600		800		1000		1200		1500		1700
full stroke range, min:	600 in.	:	800 in.	:	1000 in.	:	1200 in.	:	1500 in.	:	1700 in.
cable tension (±35%):	27 oz.	:	24 oz.	:	20 oz.	:	19 oz.	:	18 oz.	:	17 oz.
	.034-in. dia.		.019-in. dia.		.019-in. dia.		.019-in. dia.	:	.014-in. dia.		.014-in. dia.
measuring cable:	nylon-coated		nylon-coated		nylon-coated		nylon-coated		nylon-coated	:	nylon-coated
	stainless		stainless		stainless		stainless	-	stainless	:	stainless

Enclosure Material:

♠ order code:	AL	SS
enclosure material:	powder-painted aluminum	303 stainless steel
max. acceleration:	1g	1g
max. velocity:	60 inches/sec.	60 inches/sec.

Cable Exit:



Baud Rate:

Node ID:

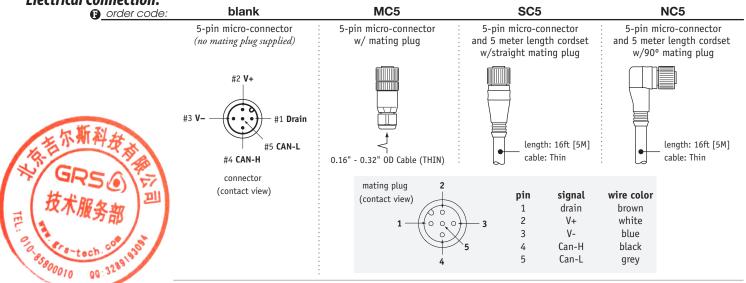
ne. ng order code:	125	250	500
_	125 kbaud	250 kbaud	500 kbaud

3 select address (0 - 63 Decimal)



6 order code:

0



2

version: 11.0 last updated: January 22, 2016