## SGH

## CANopen Output Signal

## Compact Mid-Range String Pot • Absolute Position

80, 120-inch Stroke Range Options
Rugged Polycarbonate Enclosure • IP67
In Stock for Quick Delivery
GENERAL

| Stroke Range Options 80 inches | inches (2032 mm), 120 inches ( 3048 mm ) |
| :---: | :---: |
| Accuracy | .5\% FS |
| Repeatability | .05\% FS |
| Resolution | 12-bit |
| Input Voltage | 10-36 VDC |
| Input Current | 100 mA , max |
| Measuring Cable .019-inch | 019-inch dia. nylon-coated stainless steel |
| Measuring Cable Tension, 80-inch | h $\quad 14 \mathrm{oz}$. (3,9 N) $\pm 30 \%$ |
| Measuring Cable Tension, 120-inch | ch $9 \mathrm{oz} .(2,5 \mathrm{~N}) \pm 30 \%$ |
| Maximum Acceleration | 10 g |
| Sensor plasti | plastic-hybrid precision potentiometer |
| Cycle Life | $\geq 250,000$ |
| Electrical Connection M12 | M12 connector (mating plug included) |
| Enclosure | glass-filled polycarbonate |
| Environmental | IP 67 |
| Operating Temperature | $-40^{\circ}$ to $185^{\circ} \mathrm{F}\left(-40^{\circ}\right.$ to $\left.85^{\circ} \mathrm{C}\right)$ |
| Weight, 80-inch (not including bracket) | bracket) . $6 \mathrm{lbs}(272 \mathrm{~g})$ |
| Weight, 120-inch (not including bracket) | bracket) $1 \mathrm{lb} .(454 \mathrm{~g})$ |

## CANopen SPECIFICATIONS

Communication Profile
CiA 301 V 4.0.2, CANopen Slave
Device Type
CiA 406 V3.2, Encoder
Vendor ID
Company x0002E0, Dept x00
Node ID 1-127 (Adjustable via dipswitch or LSS, default set to 1)
Baud Rate Options 125K (default), 250K, 500K, 1M

Data Rate
50ms (default)
Error Control Heartbeat, Emergency Message
PDO
2 TxPDO, 0 RxPDO, no linking, static mapping
PDO Modes
Event / Time triggered, Synch / Asynch
SDO
1 server, 0 client

| Position Data | Object Dictionary 6004 |
| :--- | ---: |
| Cam Switches | Not Supported |
| Termination Resistor | See OrderingIñorñation |


$\vdash 3.8^{\prime \prime}[96 \mathrm{~mm}]-$

$\vdash \quad 5.2^{\prime \prime}[131 \mathrm{~mm}] \quad \dashv \quad-2.6^{\prime \prime}[66 \mathrm{~mm}] \mapsto$

A perfect solution for both OEM and single-piece user, this string pot provides an economically priced CANopen sensor for 80 -inch and 120 -inch stroke range applications. This sensor is constructed with a rugged polycarbonate enclosure, a stainless steel mounting bracket and universally accepted M12 connector for operation in both outdoor or factory dry environments. For the OEM, customized options are available.

## ORDERING INFORMATION

w/o terminating resistor

## II SGH-80-4

80 -inch stroke range, no terminating resistor 5-pin M12 mating plug, mounting bracket.

SGH-120-4
120-inch stroke range, no terminating resistor 5-pin M12 mating plug, mounting bracket.
$\mathrm{w} /$ terminating resistor


5-pin M12 connectar
$\left.\quad \begin{array}{l}5-\text { pin M12 con } \\ 16 t(5 \mathrm{~m}) \\ 22 \text { AWG (.50m }\end{array}\right)$ Vi $\begin{aligned} & 16 \mathrm{ft}(5 \mathrm{~m}) \\ & \left.22 \text { AWG (. } 50 \mathrm{~mm}^{2}\right)\end{aligned}$
 M12 connector

Part No. SGH-80-4-TR

80 -inch stroke range, terminating resistor, 5-pin M12 mating plug, mounting bracket.

## Optional

 Cordset
## Part No.

SGH-120-4-TR
80-inch stroke range, terminating resistor, 5-pin M12 mating plug, mounting bracket.

Part No
9036810-0030
or short-run connections, a convenient optional $16-\mathrm{ft}$. cordset with a 5-pin M12 connector.

Field Installable Part No. Connector

9036810-0032
While every SGH ships with a field installable 5-pin M12 mating plug, additional connectors are available.


Position Data Overview:


Internal Controller Board



## LSS, Baud Rate and Node ID settings:

LSS, Baud Rate and Node ID settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body. Be careful not to damage the small gage wires that connect the potentiometer to the controller board mounted directly to the rear cover.

Follow the instructions below for desired settings and reinstall sensor cover.

Settings (cont.):


## LSS Settings:

IF DIP Switch 1 is set to "on" position, then LSS will be functional and uses the contents of EEPROM including Node ID and Baud Rate. If DIP Switch 1 is set to "off" position, then DIP switches will override information in EEPROM including the Node ID and Baud Rate.


| BAUD Rate: |  | baud rate | SW2 | SW3 |
| :---: | :---: | :---: | :---: | :---: |
| If DIP Switch 1 is set to "off" then BAUD rate is set via DIP switch 2 and 3 as shown : | transmission rate options | 125 kbps | off | off |
|  |  | 250 kbps | on | off |
|  |  | 500 kbps | off | on |
|  |  | 1 Mbps | on | on |



Manufacturer Objects:

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 2000 |  | Raw Position Value |  | This is the averaged, non-scaled value from the encoder. |
| 2001 |  | Emergency Buffer Distance | 0.1 | Emergency Message is sent when the output of the sensing potentiometer is outside it's calibrated range by more than . $1 \%$ of the sensors full measurement range (Emergency Buffer). This allows for non-repeatability of sensor and customers application. This object allows user ability to change buffer size along with transmission of Emergency Message, Manufacturer specific bit in error register set, and error added to error list. |

Device Profile Area:

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 6000 |  | Operating Parameters | $0 \times 0000$ |  |
| 6004 |  | Position Value | 0 | Counts proportional to measuring cable extension. Nominal values are $0 \times 008$ with cable fully retracted and 0xFE5 with cable fully extended. Format of data in CAN message is little endian - least significant byte pair first. Therefore $0 \times 008$ would be shown as " 0800 " and 0xFE5 would be shown as "E5 0F" |
| 6400 |  | Area State Register |  | SubNumber $=2$ (indicates underflow or overflow per CiA406) |
|  | 0 | Highest Subindex | $0 \times 01$ |  |
|  | 1 | Work Area State Channel 1 | 0 |  |

Device Profile Area (cont.):

| 6401 |  | Work Area Low Limit |  | The averaged, non-scaled (raw) encoder data below which the encoder is out of range. |
| :---: | :---: | :---: | :---: | :---: |
|  | 0 | Highest Subindex | $0 \times 01$ |  |
|  | 1 | Work Area Low Limit Channel1 | 0x024 |  |
| 6402 |  | Work Area High Limit |  | The averaged, non-scaled (raw) encoder data above which the encoder is out of range. |
|  | 0 | Highest Subindex | $0 \times 01$ |  |
|  | 1 | Work Area High Limit Channel 1 | 0xF4E |  |
| 6500 |  | Operating Status | $0 \times 0000$ |  |
| 6501 |  | Measuring Step | 1 | Position Measuring Step. Can be set by user to convert Position Value (Object 6004) to measurement units (inches, mm). Default is set to 1 . |

## Communication Area Profile:

| Index | Sub-Index | Name | Default | Comment |
| :---: | :---: | :---: | :---: | :---: |
| 1000 |  | Device Type | 0X00080196 | Device Profile 406 |
| 1001 |  | Error Register | 0 | Manufacturer Specific Error bit 7 is set when sensor is outside of calibrated range and cleared when back in range. |
| 1003 |  | Pre-Defined Error Field |  | SubNumber= 9 (lists last eight Emergency Messages) |
|  | 0 | Number of Errors | 0 |  |
|  | 1 | Standard Error Field 1 |  |  |
|  | 2 | Standard Error Field 2 |  |  |
|  | 3 | Standard Error Field 3 |  |  |
|  | 4 | Standard Error Field 4 |  |  |
|  | 5 | Standard Error Field 5 |  |  |
|  | 6 | Standard Error Field 6 |  |  |
|  | 7 | Standard Error Field 7 |  |  |
|  | 8 | Standard Error Field 8 |  |  |
| 1005 |  |  |  |  |
| 1010 |  | Store Parameters |  | SubNumber=2 |
| 1010 | 0 | Highest Subindex | $0 \times 01$ | Only "Save All Parameters" feature supported |
|  | 1 | Save All Parameters |  | Write "save" or "evsa" to save parameters to EEPROM. They are automatically loaded on power up/reset. Saves the value of all R/W object dictionary entries. |
| 1014 |  | Emergency COB-ID | $\begin{aligned} & \text { \$NodeID + } \\ & \text { 0x80 } \end{aligned}$ | COB-ID Emergency Message |
| 1015 |  | Emergency Inhibit Time | 0 | Multiple of 100us. Minimum time between transmissions of emergency messages. |
| 1017 |  | Producer Heartbeat Time | 0 | Multiples of 1 ms . Time between transmission of heartbeat messages. $0=$ disabled |

## Communication Area Profile (cont.):



80-inch SGH-80-4 w/ Mounting Bracket:

eyelet detail


120-inch SGH-120-4 w/ Mounting Bracket:

eyelet detail


## Mounting Options:

## Changing Measuring Cable Exit and Electrical Connector Direction:

For the ultimate in flexibility, the measuring cable exit direction and the direction of the electrical connector can be rotated around in $90^{\circ}$ increments to accommodate just about any installation requirement.

To change measuring cable exit direction, simply remove the 4 mounting bracket screws, rotate the bracket to desired position and replace the screws.

To change the direction of the electrical connector, remove the 4 sensor cover screws and carefully remove the sensor cover just far enough to separate the cover from the main body. Be careful of the three small gage wires that attach the internal controller board to the potentiometer.

Mounting Option Mounting Dimensions (SGH-80-4):


Mounting Option Mounting Option Dimensions (SGH-120-4):


