SR₁J

Industrial • CANBus J1939

Two Available Stroke Ranges: 0-125 in & 0-175 in.
Rugged Polycarbonate Enclosure • Simple Installation
Designed for Outdoor & IP67 environments
In Stock for Quick Delivery!

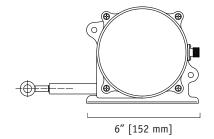
SPECIFICATIONS

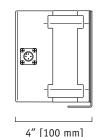
| Full Stroke Range, SR1J-125 | 125 inches (3175 mm), maximum |
|------------------------------------|--|
| Full Stroke Range, SR1J-175 | 175 inches (4445 mm), maximum |
| Repeatability | .05% FS. |
| Resolution | 12-bit |
| Input Voltage | 10-36 VDC |
| Input Current | 100 mA, max. |
| Maximum Velocity | 80 inches (2 meters) per second |
| Maximum Acceleration | 10 g (retraction) |
| Measuring Cable Tension | 23 oz. (6,4 N) ±30% |
| Sensor | plastic-hybrid precision potentiometer |
| Cycle Life | 250,000 (potentiometer) |
| Enclosure | polycarbonate |
| Measuring Cable | .031-inch dia. bare stainless rope |
| Electrical Connection | M12 Connector (mating plug included) |
| Environmental Suitability | NEMA 6, IP67 |
| Operating Temperature | -40° to 185° F (-40° to 85° C) |
| Weight | 2.5 lbs. (1.3 Kg) |

CANopen SPECIFICATIONS

| Communication Profile | CANbus SAE J1939 |
|-----------------------|---|
| Protocol | Proprietary B |
| Node ID | Adjustable via dipswitch (0-63), default set to 0 |
| Baud Rate Options | 125K (default), 250K, 500K |
| Data Rate Options | 5ms (default), 20ms, 50ms, 100ms |







The SR1J is a rugged, low-cost, easy to install high performance string pots built for wet environments and outdoor applications.

The SR1J comes in two ranges: 0-125 inches and 0-175 inches and is the perfect low-cost J1939 CANbus solution for mobile applications such as mobile crane outrigger position or hydraulic lifts. Every unit ships with a handy mounting bracket giving the user the ultimate flexibility to easily orient the measuring cable to one of four different directions.

ORDERING INFORMATION



SR1J-125

125-inch stroke range, CANBus J1939 communication, 5-pin M12 mating plug & mounting bracket included.



SR1J-175

175-inch stroke range, CANBus J1939 communication, 5-pin M12 mating plug & mounting bracket included.



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for short-run connections, optional 16-ft (5 m) long cordset with 5-pin M12 mating plug.

20630 Plummer Street - Chatsworth, CA 91311 - Meas-Spec.com tel: 800.423.5483 • +1.818.701.2750 • fax: +1.818.701.2799

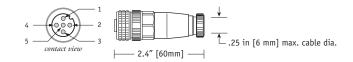


formally Celesco Transducer Products, Inc.

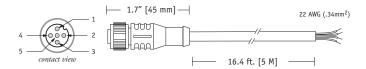
Electrical Connection

| output signal | connector pin | colorcode (cordset) |
|------------------|------------------|------------------------|
| drain | 1 | brown |
| 1036 VDC | 2 | white |
| common | 3 | blue |
| CAN high | 4 | black |
| CAN low | 5 | green/yellow |

M12 Connector (included)



16 ft. Cordset (optional)

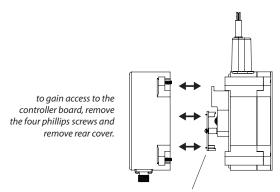


Internal Controller Board

LSS, Baud Rate and Node ID settings:

LSS, Baud Rate and Node ID settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body.

Follow the instructions on the following pages for desired settings and reinstall sensor cover.

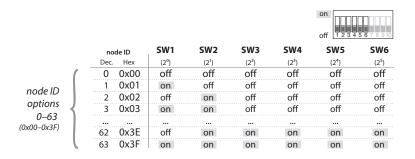


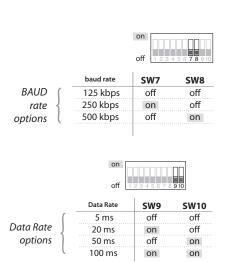
LSS, Baud Rate, Node ID Settings and Status LED located on controller board

Baud, Node ID and Data Rate:

Baud Rate, Node ID and Data Rate settings are set via dip switch found on the internal controller board. To gain access to the controller board, remove the 4 cover attaching screws and carefully separate the sensor cover from the main body. Be careful not to damage the small gage wires that connect the controller board to the connector mounted directly to the rear cover.

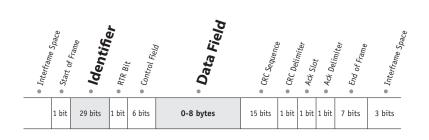
Follow the instructions below for desired settings and reinstall sensor cover.

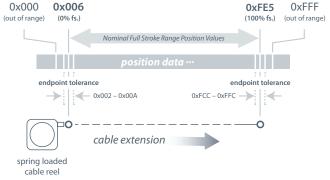




I/O Format:

Position Data Overview





Identifier:

| - | Mess | age Pr | iority | Fut U | ure se | | J1939 Reference Proprietary B | | | | Data Field Type* | | | | | | Not | Used | Node ID** | | | | | | | | | | |
|----------------------|------|--------|--------|----------|-----------|----|----------------------------------|----|----|----|------------------|----|----|----|----|----|-----|------|-----------|---|---|---|---|---|---|---|---|---|---|
| Example – | 1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| Identifier Bit No. – | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Hex Value – | | | (|) | | | | F | | | | = | | | | 5 | | | 3 | 3 | | | 3 | 3 | | | F | | |

*Sensor field data can be factory set to customer specific value. **Customer defined, set via Dips 1-6. Bit values shown for example only, see Address Setting below.

Data Field:

 $\mathbf{B_0} = \mathsf{LSB}$ current measurement count b

B₁ = MSB current measurement count

 B_2 = not used

 $\mathbf{B_3} = \text{not used}$

| t byte nt byte | $\mathbf{B_5} = \text{error flag}$ | | | | | | | | | | |
|-------------------|---|--|----------------|----------------|----------------|----------------|----|----------------|----------------|----------------|--|
| | B₆ = LSB velocity data byteB₇ = MSB velocity data byte | | B ₇ | В ₆ | B ₅ | B ₄ | В3 | B ₂ | B ₁ | В ₀ | |

Velocity Data

B₆ B₅ B₄ В₃ B₂ B₁

Current Measurement Count

The Current Measurement Count (CMC) is the output data that indicates the present position of the measuring cable. The CMC is a 12-bit value that occupies bytes B_0 and B_1 of the data field. B_0 is the LSB (least significant byte) and B_1 is the MSB (most significant byte).

The CMC starts at 0x006 with the measuring cable fully retracted and continues upward to the end of the stroke range stopping at **OxFE5**. This holds true for all ranges.

Converting CMC to Linear Measurement

To convert the current measurment count to inches or millimeters, simply divide the count by 4061 (total counts over the range) and then multiply that value by the full stroke range:

$$\left(\frac{\text{CMC} - 6}{4063}\right)$$
 x full stroke range

Sample Conversion:

If the full stroke range is 250 inches and the current position is **0x4FF** (1279 Decimal) then,

$$\left(\frac{1279-6}{4061}\right)$$
 x 250 = 78.8 inches

Error Flags



RED and GREEN Indicator LEDS (controller board)

B₇ B₆ B₅ B₄ B₃ B₂ B₁

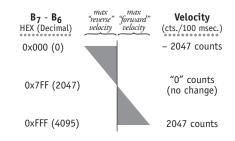
0x00 (GREEN - ON, RED - OFF) indicates the sensor is operating within normal calibrated limits.

0x33, 0x55, 0xAA, 0xCC (RED or GREEN - FLASHING) indicates sensor is at or beyond it's calibrated measurment range. Should any of these conditions occur within calibrated range, return unit to factory for evaluation or service.

| В7 | В6 | B ₅ | B ₄ | В3 | B ₂ | B ₁ | B ₀ | |
|----|----|----------------|----------------|----|----------------|----------------|----------------|--|

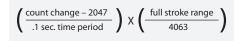
Velocity

Data in bytes $\mathbf{B_7}$ - $\mathbf{B_6}$ is the change in the CMC (current measurement count) over a 100 msec time period. This data can then be used to calculate velocity in a post processing operation.



Velocity Calculation

Error Flags



Measurement

Count

Sample Calculations

Cable Extension (positive direction):

Not Used

 $B_7..B_6 = 0x8D3$ (2259Dec), full stroke = 250 in.

$$\left(\frac{2259 - 2047}{.1 \text{ sec}}\right) X \left(\frac{250 \text{ in.}}{4063}\right) = 130.45 \text{ in.} / \text{sec.}$$

Cable Retraction (negative direction):

 $B_7..B_6 = 0x7D0$ (2000Dec), full stroke = 250 in.

$$\left(\frac{2000 - 2047}{.1 \text{ sec}}\right) \chi \left(\frac{250 \text{ in.}}{4063}\right) = -28.92 \text{ in.} / \text{sec}$$

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Changing the Cable Exit

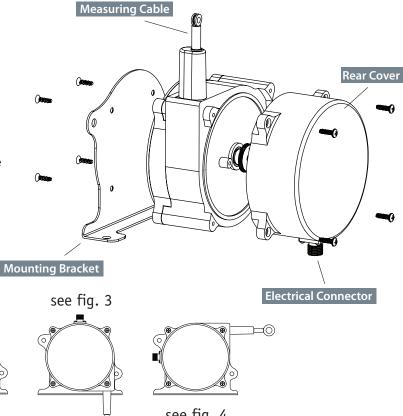
Changing Measuring Cable Exit

To change the direction of the measuring cable, remove the 4 mounting bracket screws and rotate bracket to one of four available positions. See figures 1 - 4 on the following pages for mounting dimensions.

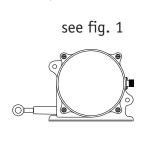
Changing Electrical Connector Direction

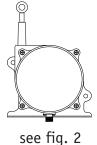
To change the position of the electrical connector, remove the 4 rear cover screws and carefully separate rear cover from the sensor body.

Rotate the rear cover to desired position being careful to not tangle the wiring harness that runs to the connector.



Cable Exit Direction Options







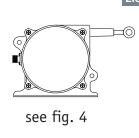
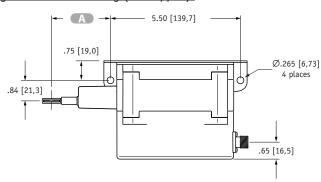
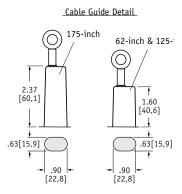
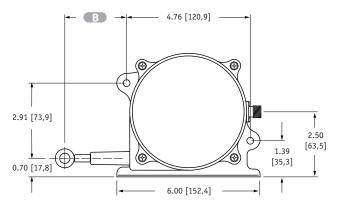


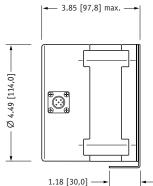
Fig. 1 - Outline Drawing (as shipped)

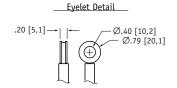


| Model | A | В |
|----------|--------------------------|---------------------------|
| 125-inch | 2.00 ±.13 [50,8 ±3,3] | 2.37 ±.13 [60,22 ±3,3] |
| 175-inch | 2.87 ±.13 [72,8 ±3,2] | 3.24 ±.13 [82.2 ±3,2] |



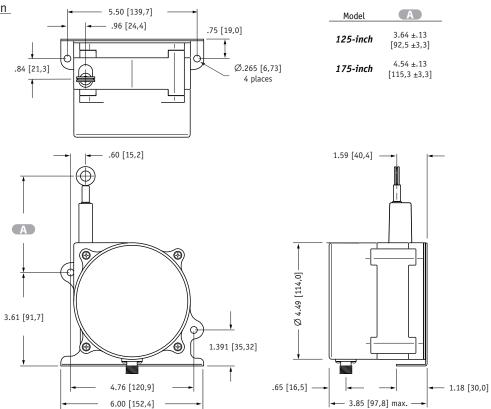






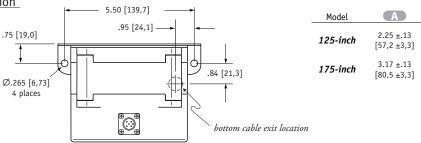
units are in inches [mm] tolerances are \pm .04 [1,0] unless otherwise noted

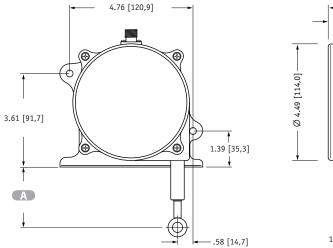
Fig. 2 - "Up" Cable Exit Direction



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Fig. 3 - "Down" Cable Exit Direction





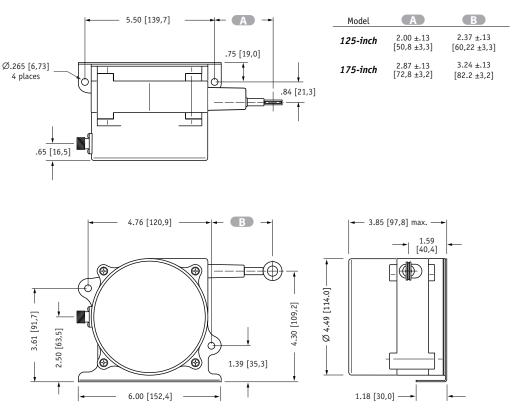
1.18 [30,0]

3.85 [97,8] max.

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formally Celesco Transducer Products, Inc.

Fig. 4 - "Rear" Cable Exit Direction



units are in inches [mm] tolerances are \pm .04 [1,0] unless otherwise noted



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